

- Part 1: Introduction inverse problems and image deconvolution
- Part 2: Introduction to Sparsity and Compressed Sensing
- Part 3: Wavelets in Astronomy: from orthogonal wavelets and to the Starlet transform.**
- Part 4: Beyond Wavelets
- Part 5: Inverse problems and their solution using sparsity: denoising, deconvolution, inpainting, blind source separation.
- Part 6: CMB & Sparsity
- Part 7: Perspective of Sparsity & Compressed Sensing in Astrophysics

Data Representation Tour

- Computational harmonic analysis seeks representations of a signal as linear combinations of basis, frame, dictionary, element :

$$s_i = \sum_{k=1}^K \alpha_k \phi_k$$

↑ ↑
coefficients basis, frame

- Fast calculation of the coefficients α_k
- Analyze the signal through the statistical properties of the coefficients

What is a good sparse representation for data?

A signal s (n samples) can be represented as sum of weighted elements of a given dictionary

Dictionary (basis, frame)

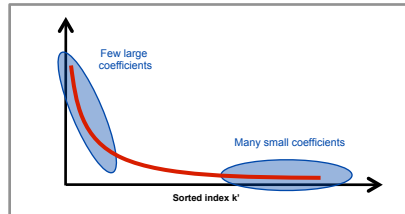
$$\Phi = \{\phi_1, \dots, \phi_K\}$$

Ex: Haar wavelet

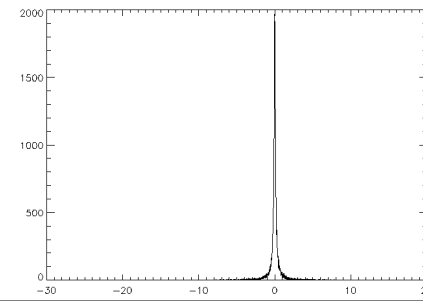
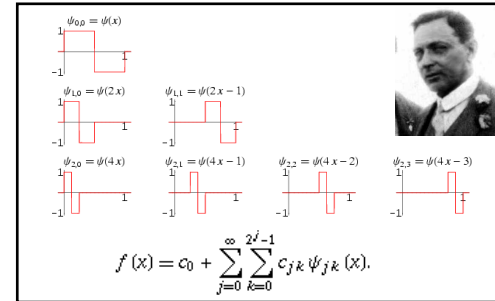
Atoms

$$s = \sum_{k=1}^K \alpha_k \phi_k = \Phi \alpha$$

coefficients



- Fast calculation of the coefficients
- Analyze the signal through the statistical properties of the coefficients
- Approximation theory uses the sparsity of the coefficients



The Great Father Fourier - Fourier Transforms

Any Periodic function can be expressed as linear combination of basic trigonometric functions

(Basis functions used are sine and cosine)



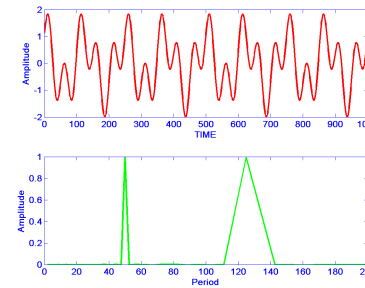
Jean-Baptiste-Joseph Fourier
(1768-1830)

$$X(f) = \int_{-\infty}^{\infty} x(t) e^{-2\pi i f t} dt$$

$$x(t) = \int_{-\infty}^{\infty} X(f) e^{2\pi i f t} df$$

Time domain

Frequency domain



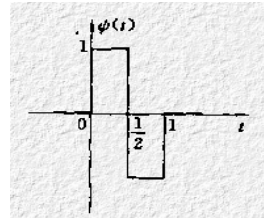
● Alfred Haar Wavelet (1909):

The first mention of wavelets appeared in an appendix to the thesis of Haar

- With *compact support*, vanishes outside of a finite interval
- Not continuously differentiable
- Wavelets are functions defined over a finite interval and having an average value of zero.

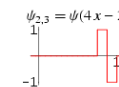
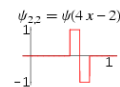
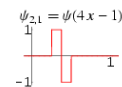
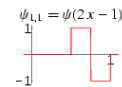
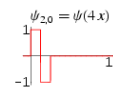
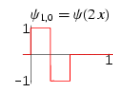
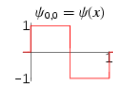


$$f(x) = c_0 + \sum_{j=0}^{\infty} \sum_{k=0}^{2^j-1} c_{jk} \psi_{jk}(x).$$



$$\Psi(x) = \begin{cases} 1 & 0 \leq x \leq \frac{1}{2} \\ -1 & \frac{1}{2} < x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

Haar wavelet

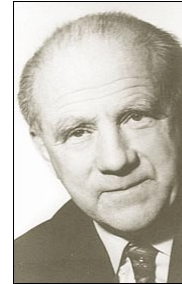


- ==> What kind of $\psi(t)$ could be useful?**
- . Impulse Function (Haar): Best time resolution**
 - . Sinusoids (Fourier): Best frequency resolution**

==> We want both of the best resolutions

==> Heisenberg, 1930
Uncertainty Principle
There is a lower bound for

$$\Delta t \cdot \Delta \omega$$



SHORT TIME FOURIER TRANSFORM (STFT)

- **Dennis Gabor (1946) Used STF**

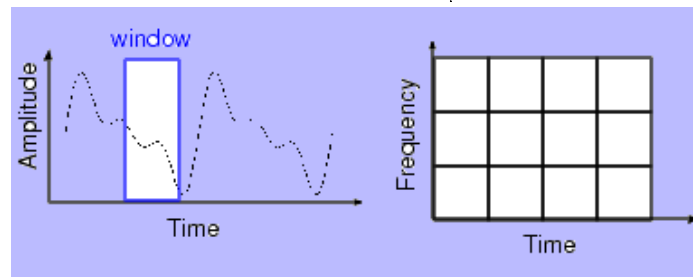
To analyze only a small section of the signal at a time -- a technique called *Windowing the Signal*.

- **The Segment of Signal is Assumed *Stationary***

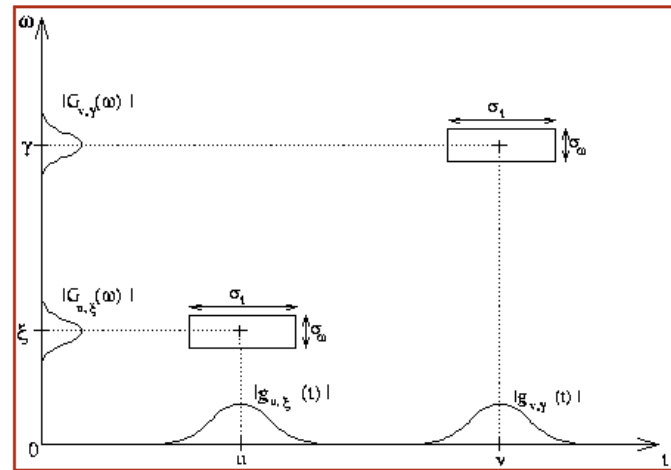
The Short Term Fourier Transform is defined by:

$$STFT(\nu, b) = \int_{-\infty}^{+\infty} \exp(-j2\pi\nu t) f(t)g(t-b)dt$$

when g is a Gaussian, it corresponds to the Gabor transform.



Heisenberg Box



$$\sigma_t^2 \sigma_\omega^2 \geq \frac{1}{4}.$$

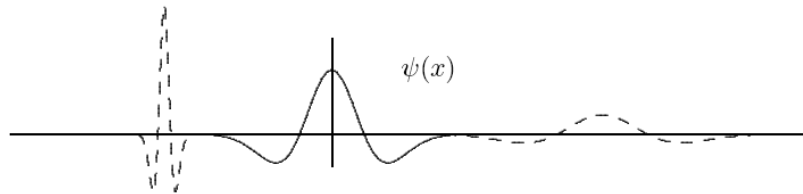
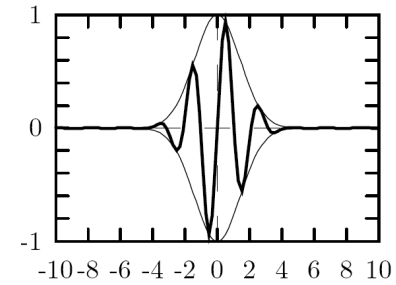
Candidate analyzing functions for piecewise smooth signals

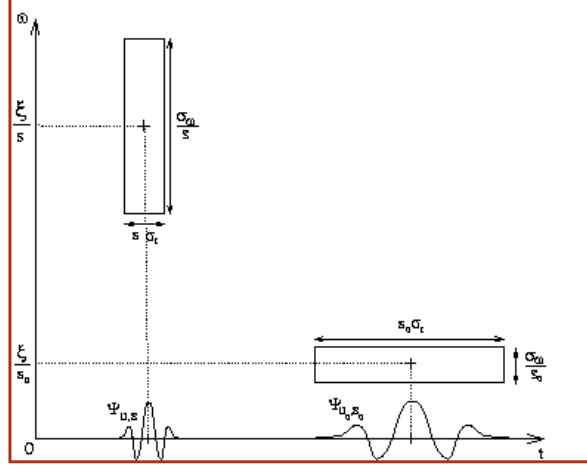
- Windowed fourier transform or Gaborlets :

$$\psi_{\omega,b}(t) = g(t-b)e^{i\omega t}$$

- Wavelets :

$$\psi_{a,b} = \frac{1}{\sqrt{a}}\psi\left(\frac{t-b}{a}\right)$$





The Continuous Wavelet Transform

$$W(a, b) = K \int_{-\infty}^{+\infty} \psi^*\left(\frac{x-b}{a}\right) f(x) dx$$

where:

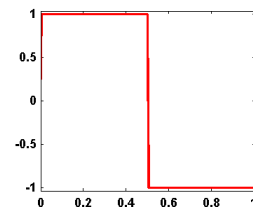
- $W(a, b)$ is the wavelet coefficient of the function $f(x)$
- $\psi(x)$ is the analyzing wavelet
- $a (> 0)$ is the scale parameter
- b is the position parameter

In Fourier space, we have: $\hat{W}(a, \nu) = \sqrt{a} \hat{f}(\nu) \hat{\psi}^*(a\nu)$

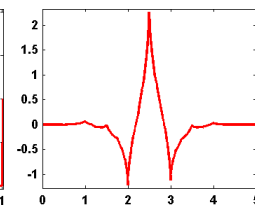
When the scale a varies, the filter $\hat{\psi}^*(a\nu)$ is only reduced or dilated while keeping the same pattern.

Some typical mother wavelets

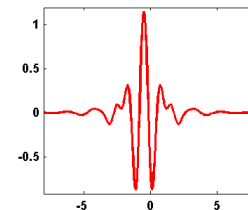
Haar



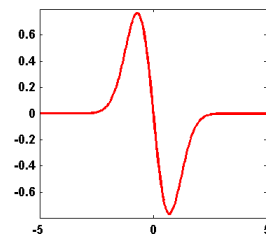
coiflet



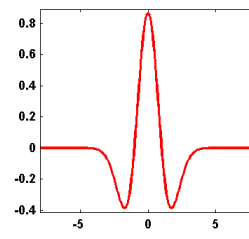
Meyr



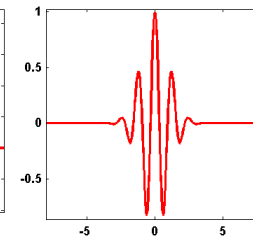
Gaussian



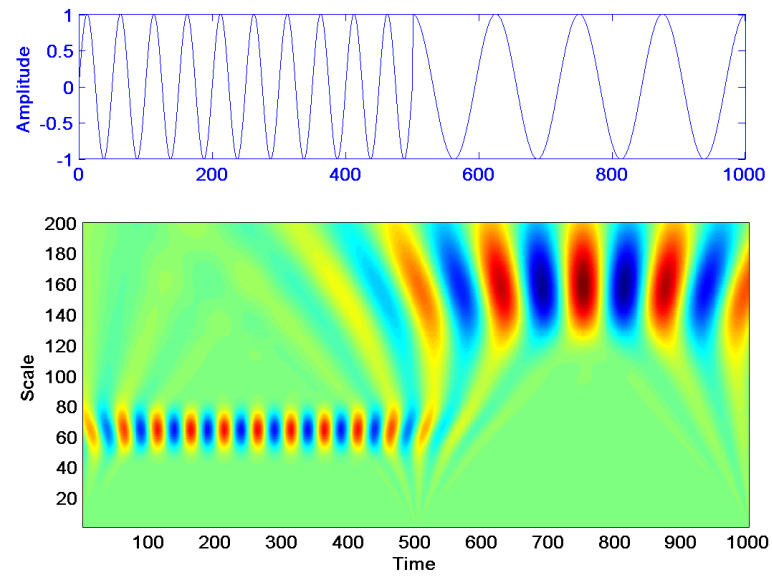
Mexican hat



Morlet



Typical picture



The Inverse Transform

The inverse transform is:

$$f(x) = \frac{1}{C_\psi} \int_{-\infty}^{+\infty} \int_0^{+\infty} \frac{1}{\sqrt{a}} W(a, b) \psi\left(\frac{x-b}{a}\right) \frac{da db}{a^2}$$

where

$$C_\psi = \int_{-\infty}^{+\infty} |\hat{\psi}(t)|^2 \frac{dt}{t} < +\infty$$

Reconstruction is only possible if C_ψ is defined (admissibility condition).

This condition implies $\hat{\psi}(0) = 0$, i.e. the mean of the wavelet function is 0.



Yves Meyer



A Major Breakthrough

Daubechies, 1988 and Mallat, 1989

Daubechies:

Compactly Supported Orthogonal and Bi-Orthogonal Wavelets

Mallat:

Theory of Multiresolution Signal Decomposition

**Fast Algorithm for the Computation of Wavelet Transform Coefficients
using Filter Banks**

Multiresolution Analysis

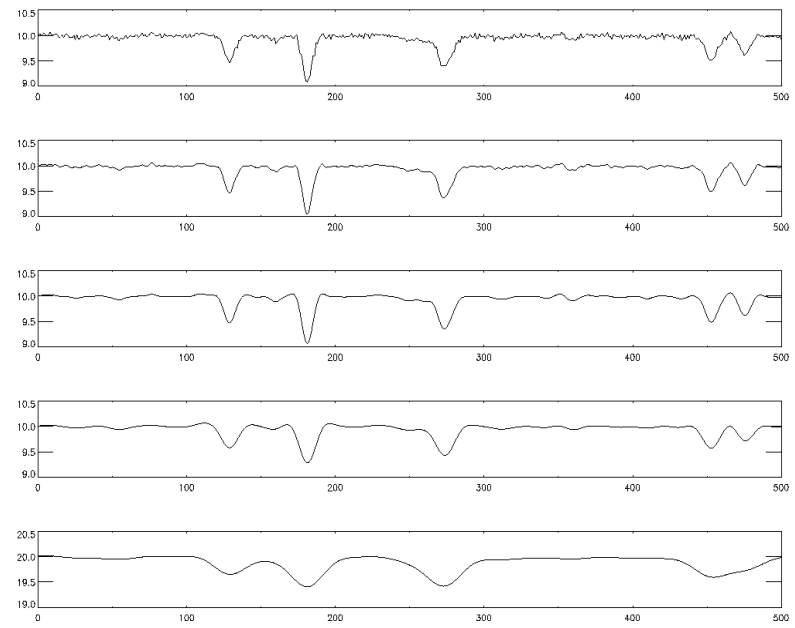
The multiresolution analysis (Mallat, 1989) results from the embedded subsets generated by the interpolations at different scales.

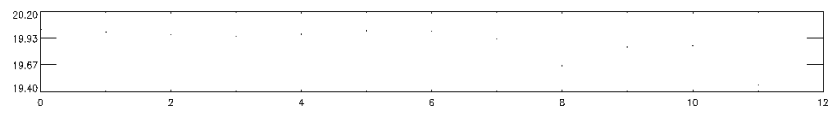
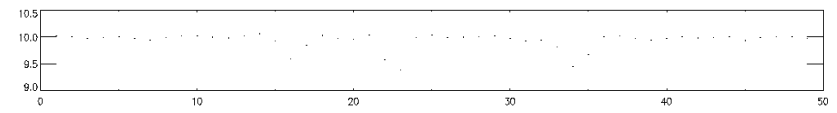
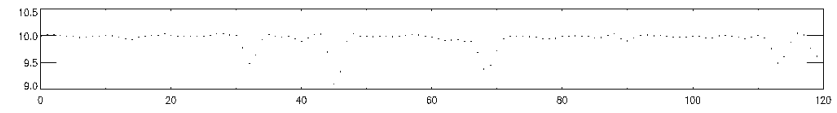
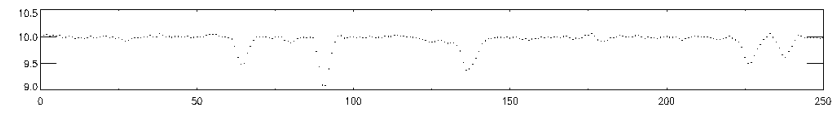
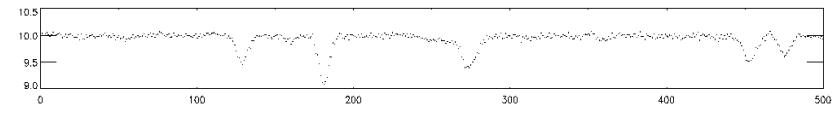
A function $f(x)$ is projected at each step j on the subset V_j ($\dots \subset V_3 \subset V_2 \subset V_1 \subset V_0$). This projection is defined by the scalar product $c_{j,k}$ of $f(x)$ with the scaling function $\phi(x)$ which is dilated and translated:

$$c_{j,k} = \langle f(x), \phi_{j,k}(x) \rangle$$

$$\phi_{j,k}(x) = 2^{-j} \phi(2^{-j}x - k)$$

where $\phi(x)$ is the scaling function. ϕ is a low-pass filter.





Wavelets and Multiresolution Analysis

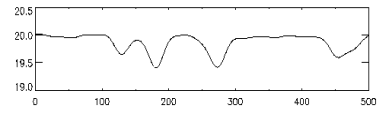
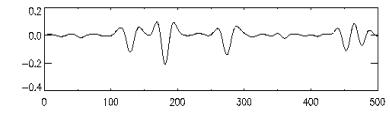
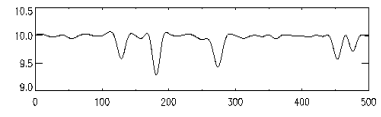
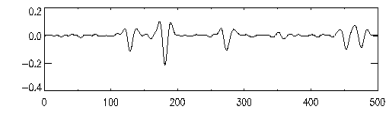
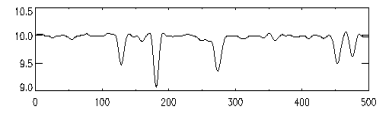
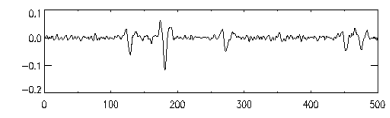
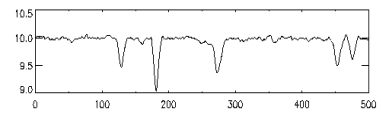
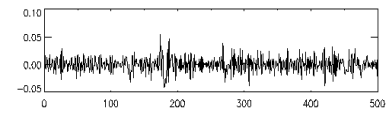
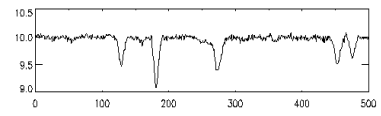
The difference between c_j and c_{j+1} is contained in the detail signal belonging to the space O_{j+1} orthogonal to V_{j+1} .

$$O_{j+1} \oplus V_{j+1} = V_j$$

The set $\{\sqrt{2^{-j}}\psi(2^{-j}x - k)\}_{k \in \mathbb{Z}}$ form a basis of O_j . $\psi(x)$ is the wavelet function.

the wavelet coefficients are obtained by:

$$w_{j,k} = \langle f(x), 2^{-j}\psi(2^{-j}x - k) \rangle$$



the Fast Wavelet Transform

As $\phi(x)$ is a scaling function which has the property:

$\frac{1}{2}\phi(\frac{x}{2}) = \sum_n h(n)\phi(x-n)$. $c_{j+1,k}$ can be obtained by direct computation from $c_{j,k}$

$$c_{j+1,k} = \sum_n h(n-2k)c_{j,n}$$

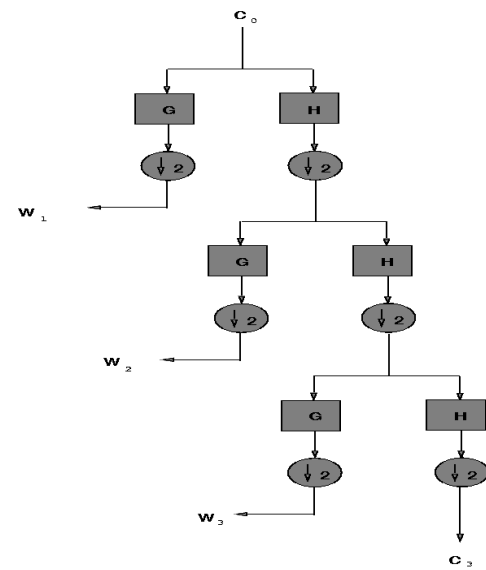
and $\frac{1}{2}\psi(\frac{x}{2}) = \sum_n g(n)\phi(x-n)$.

The scalar products $\langle f(x), 2^{-(j+1)}\psi(2^{-(j+1)}x-k) \rangle$ are computed with:

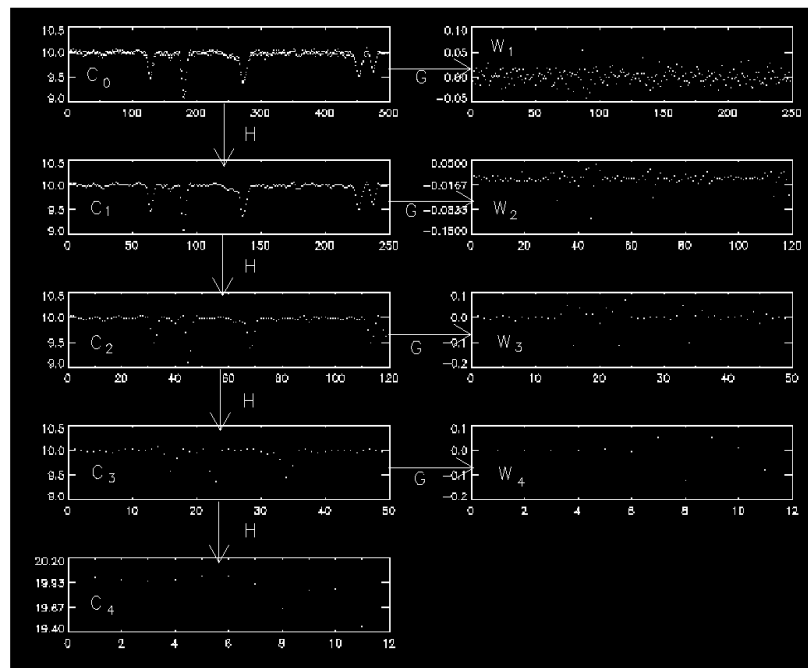
$$w_{j+1,k} = \sum_n g(n-2k)c_{j,n}$$

Reconstruction by:

$$c_{j,k} = 2 \sum_n h(k-2n)c_{j+1,n} + g(k-2n)w_{j+1,n}$$



 Keep one sample out of two

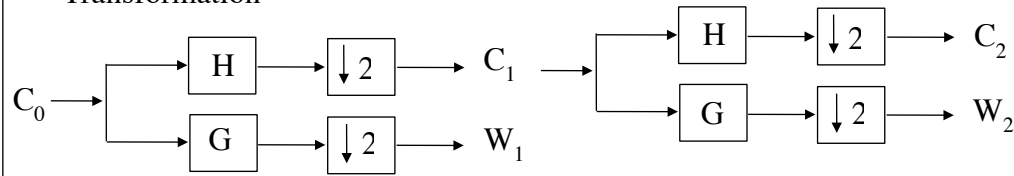


64	48	16	32	56	56	48	24
56	24	56	36	8	-8	0	12
40	46	16	10	8	-8	0	12
43	-3	16	10	8	-8	0	12

The Orthogonal Wavelet Transform (OWT)

$$s_l = \sum_k c_{J,k} \phi_{J,l}(k) + \sum_k \sum_{j=1}^J \psi_{j,l}(k) w_{j,k}$$

Transformation



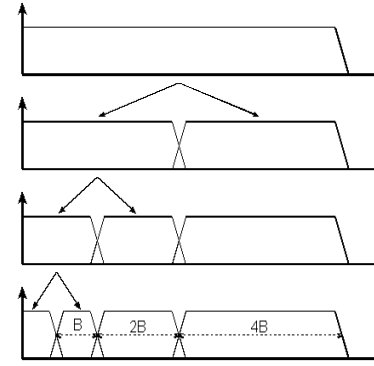
$$c_{j+1,l} = \sum_h h_{k-2l} c_{j,k} = (\bar{h} * c_j)_{2l}$$

$$w_{j+1,l} = \sum_h g_{k-2l} c_{j,k} = (\bar{g} * c_j)_{2l}$$

Reconstruction:

$$c_{j,l} = \sum_k \tilde{h}_{k+2l} c_{j+1,k} + \tilde{g}_{k+2l} w_{j+1,k} = \tilde{h} * \tilde{c}_{j+1} + \tilde{g} * \tilde{w}_{j+1}$$

$$\tilde{x} = (x_1, 0, x_2, 0, x_3, \dots, 0, x_j, 0, \dots, x_{n-1}, 0, x_n)$$



At two dimensions, we separate the variables x,y:

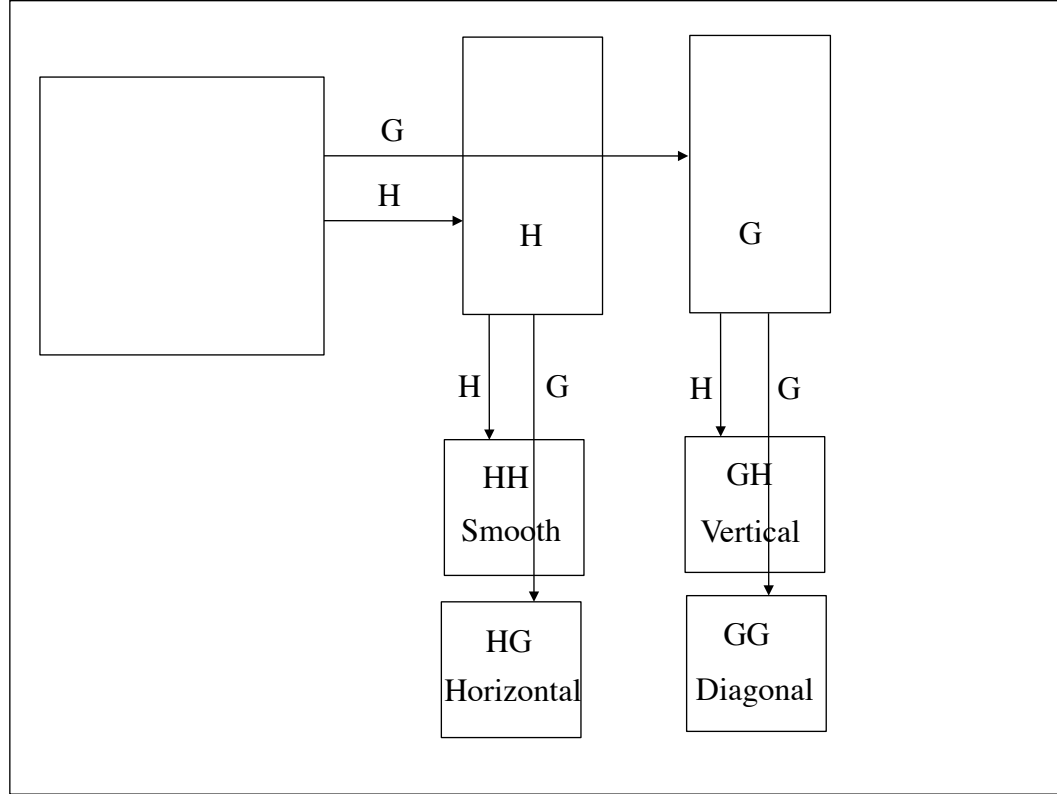
- vertical wavelet: $\psi^1(x, y) = \phi(x)\psi(y)$
- horizontal wavelet: $\psi^2(x, y) = \psi(x)\phi(y)$
- diagonal wavelet: $\psi^3(x, y) = \psi(x)\psi(y)$

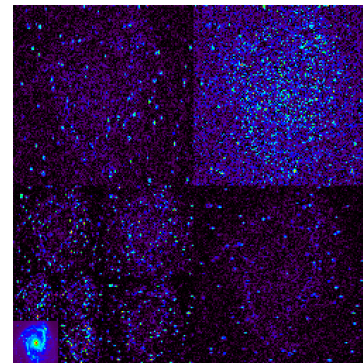
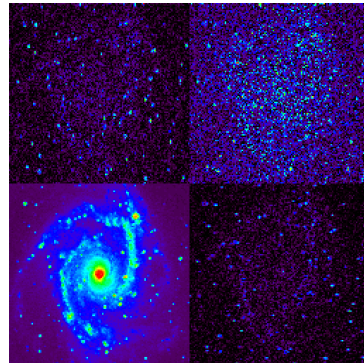
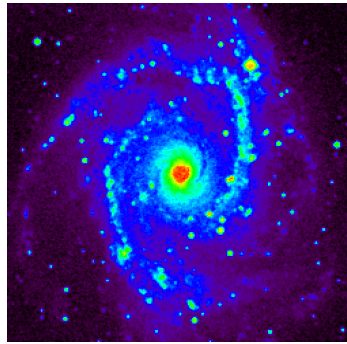
The detail signal is contained in three sub-images

$$w_j^1(k_x, k_y) = \sum_{l_x=-\infty}^{+\infty} \sum_{l_y=-\infty}^{+\infty} g(l_x - 2k_x)h(l_y - 2k_y)c_{j+1}(l_x, l_y)$$

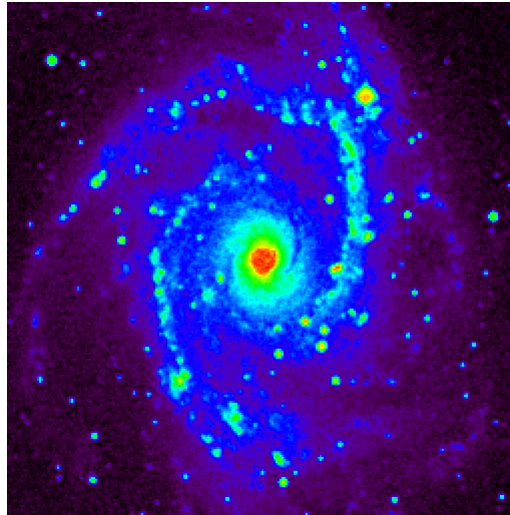
$$w_j^2(k_x, k_y) = \sum_{l_x=-\infty}^{+\infty} \sum_{l_y=-\infty}^{+\infty} h(l_x - 2k_x)g(l_y - 2k_y)c_{j+1}(l_x, l_y)$$

$$w_j^3(k_x, k_y) = \sum_{l_x=-\infty}^{+\infty} \sum_{l_y=-\infty}^{+\infty} g(l_x - 2k_x)g(l_y - 2k_y)c_{j+1}(l_x, l_y)$$

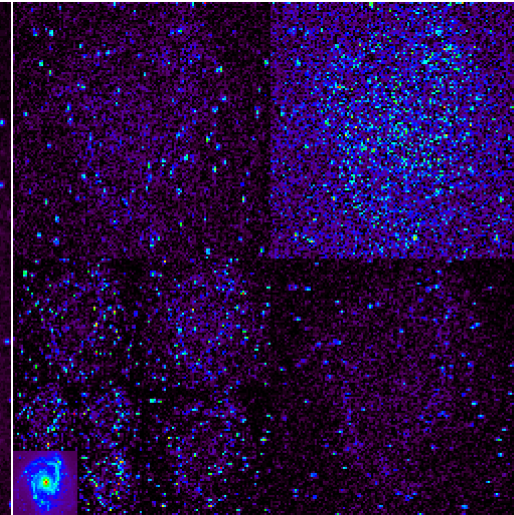




NGC2997



NGC2997 WT



JPEG/JPEG 2000

Original BMP

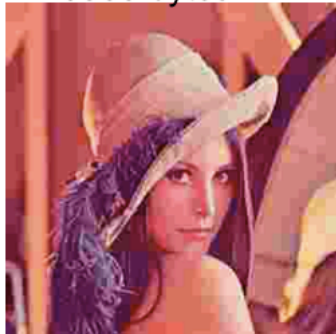
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JPEG 1:68

3983 bytes

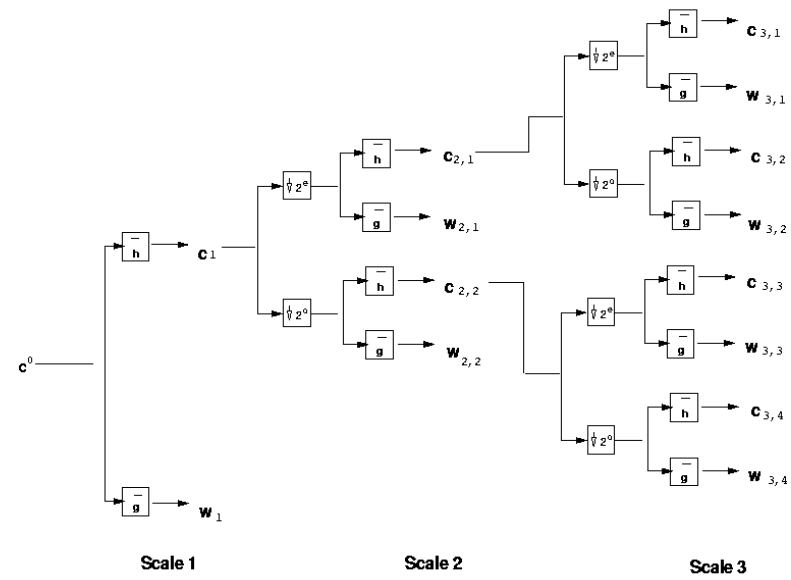


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3876 bytes



1D undecimated wavelet transform



The à trous Algorithm

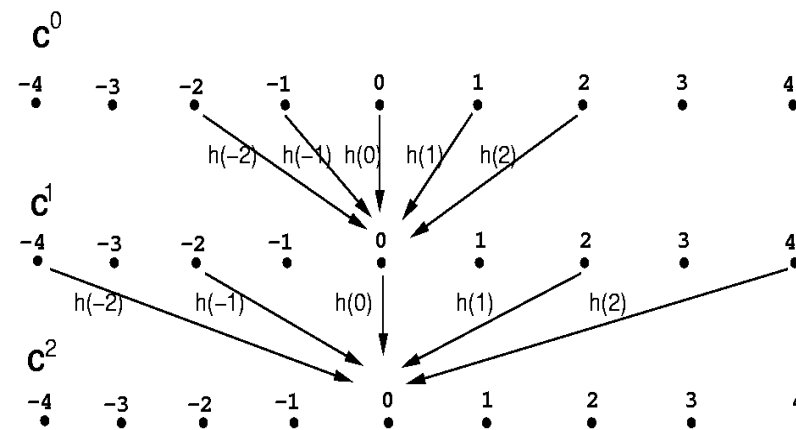
It exists however a very efficient way to implement it. The “à trous” algorithm consists in considering the filter $h^{(j)}$ instead of h where $h_l^{(j)} = h_l$ if $l/2^j$ is an integer and 0 otherwise. For example, we have $h^{(1)} = (\dots, h_{-2}, 0, h_{-1}, 0, h_0, 0, h_1, 0, h_2, \dots)$. Then $c_{j+1,l}$ and $w_{j+1,l}$ can be expressed by:

$$\begin{aligned} c_{j+1,l} &= (\bar{h}^{(j)} * c_j)_l = \sum_k h_k c_{j,l+2^j k} \\ w_{j+1,l} &= (\bar{g}^{(j)} * c_j)_l = \sum_k g_k c_{j,l+2^j k} \end{aligned}$$

The reconstruction is obtained by:

$$c_j = \frac{1}{2}(\tilde{h}^{(j)} * c_{j+1} + \tilde{g}^{(j)} w_{j+1})$$

Passage from c_0 to c_1 , and from c_1 to c_2

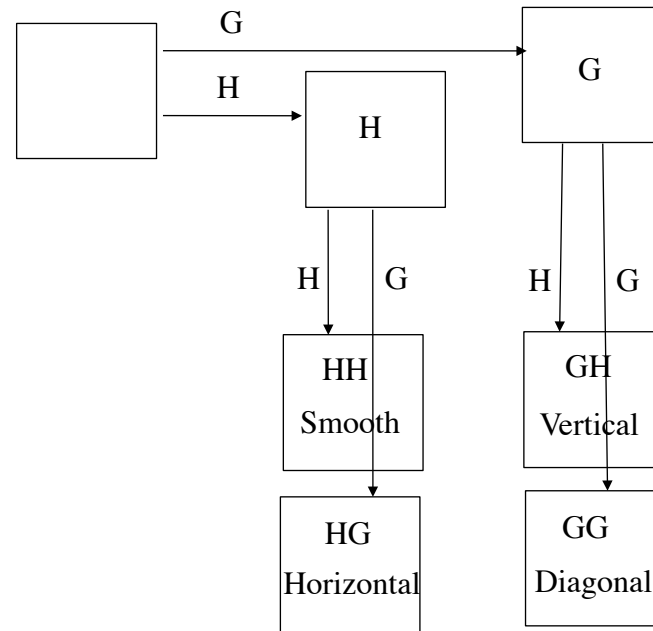


2D Undecimated Wavelet Transform

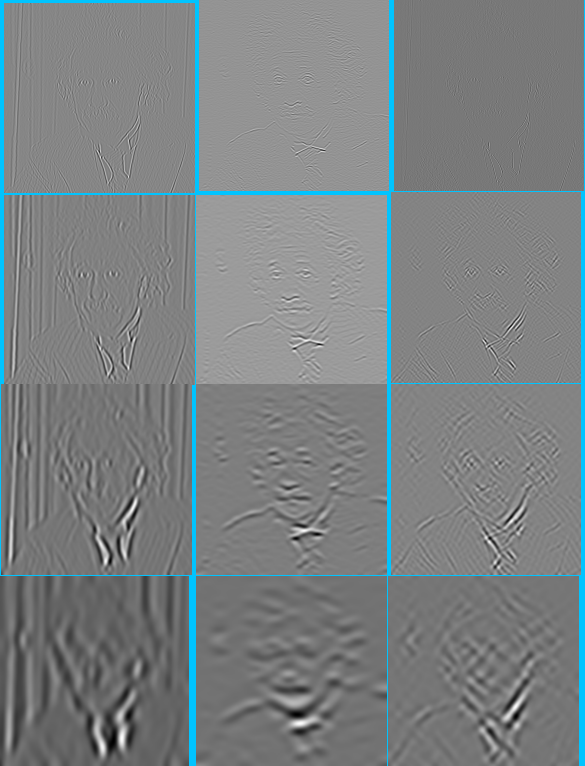
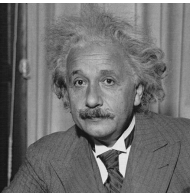
The à trous algorithm can be extended to 2D:

$$\begin{aligned}c_{j+1,k,l} &= (\bar{h}^{(j)} \bar{h}^{(j)} * c_j)_{k,l} \\w_{j+1,1,k,l} &= (\bar{g}^{(j)} \bar{h}^{(j)} * c_j)_{k,l} \\w_{j+1,2,k,l} &= (\bar{h}^{(j)} \bar{g}^{(j)} * c_j)_{k,l} \\w_{j+1,3,k,l} &= (\bar{g}^{(j)} \bar{g}^{(j)} * c_j)_{k,l}\end{aligned}$$

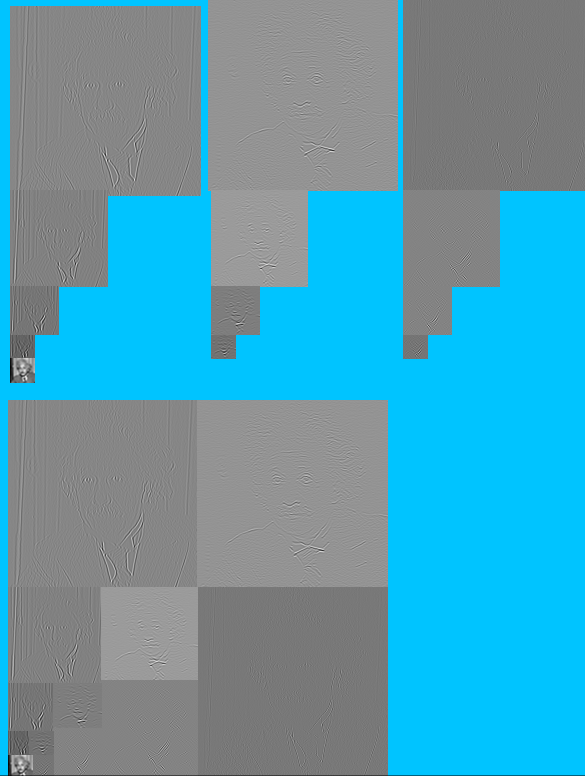
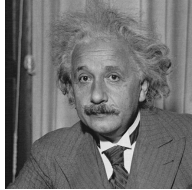
where $hg * c$ is the convolution of c by the separable filter hg (i.e convolution first along the columns per h and then convolution along the lines per g).

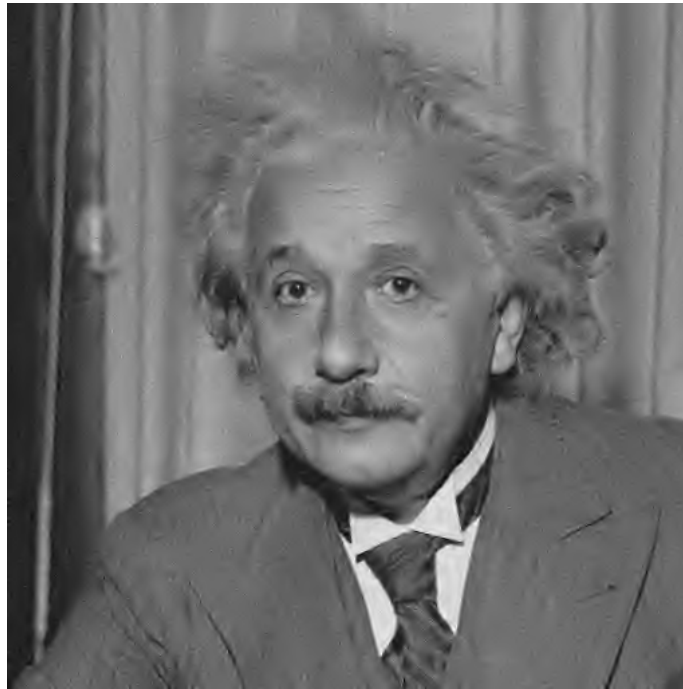


**Undecimated
Wavelet
Transform**



**Partially
Undecimated
Wavelet
Transform**





Hard Threshold: 3sigma					
OWT			UWT		
Redundancy	1	4	7	10	13
PSNR(dB)	28.90	30.58	31.51	31.83	31.89
Square Error	83.54	52.28	45.83	42.51	41.99

ISOTROPIC UNDECIMATED WT: The Starlet Transform

• Isotropic transform well adapted to astronomical images.

• Diadic Scales.

• Invariance per translation.

Scaling function and dilation equation:

$$\frac{1}{4} \varphi\left(\frac{x}{2}, \frac{y}{2}\right) = \sum_{l,k} h(l,k) \varphi(x-l, y-k)$$

Wavelet function decomposition:

$$\frac{1}{4} \psi\left(\frac{x}{2}, \frac{y}{2}\right) = \sum_{l,k} g(l,k) \varphi(x-l, y-k)$$

A trous wavelet

transform: $w_j(x,y) = \langle f(x,y), \frac{1}{4^j} \varphi\left(\frac{x-l}{2^j}, \frac{y-k}{2^j}\right) \rangle$

Generally, the wavelet resulting from the difference between two successive approximations is applied:

$$w_{j+1,k} = c_{j,k} - c_{j+1,k}$$

The associated wavelet is $\psi(x)$.

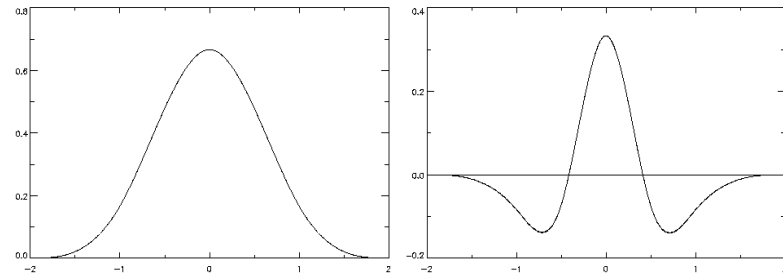
$$\frac{1}{2}\psi\left(\frac{x}{2}\right) = \phi(x) - \frac{1}{2}\phi\left(\frac{x}{2}\right)$$

The reconstruction algorithm is immediate:

$$c_{0,k} = c_{J,k} + \sum_{j=1}^J w_{j,k}$$

The Isotropic Wavelet and Scaling Functions

$$\begin{aligned}
 B_3(x) &= \frac{1}{12}(|x-2|^3 - 4|x-1|^3 + 6|x|^3 - 4|x+1|^3 + |x+2|^3) \\
 \psi(x, y) &= B_3(x)B_3(y) \\
 \frac{1}{4}\psi\left(\frac{x}{2}, \frac{y}{2}\right) &= \phi(x, y) - \frac{1}{4}\phi\left(\frac{x}{2}, \frac{y}{2}\right)
 \end{aligned}$$



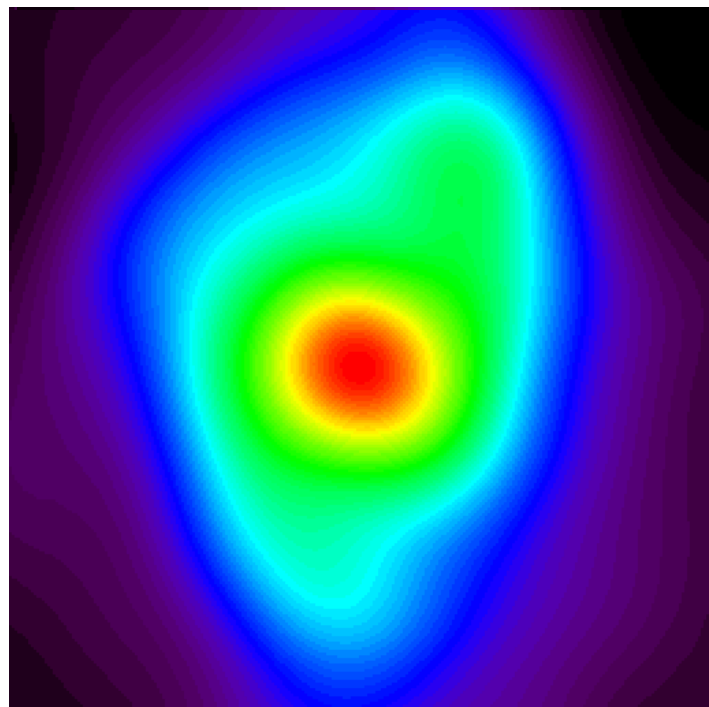
$$\begin{pmatrix} \frac{1}{16} & \frac{1}{4} & \frac{3}{8} & \frac{1}{4} & \frac{1}{16} \end{pmatrix} \otimes \begin{pmatrix} 1/16 \\ 1/4 \\ 3/8 \\ 1/4 \\ 1/16 \end{pmatrix} = \begin{pmatrix} \frac{1}{256} & \frac{1}{64} & \frac{3}{128} & \frac{1}{64} & \frac{1}{256} \\ \frac{1}{64} & \frac{1}{16} & \frac{3}{32} & \frac{1}{16} & \frac{1}{64} \\ \frac{3}{128} & \frac{3}{32} & \frac{9}{64} & \frac{3}{32} & \frac{3}{128} \\ \frac{1}{64} & \frac{1}{16} & \frac{3}{32} & \frac{1}{16} & \frac{1}{64} \\ \frac{1}{256} & \frac{1}{64} & \frac{3}{128} & \frac{1}{64} & \frac{1}{256} \end{pmatrix}$$

In the 2-dimensional case, we assume the separability, which leads to a row-by-row convolution with $(\frac{1}{16}, \frac{1}{4}, \frac{3}{8}, \frac{1}{4}, \frac{1}{16})$; followed by column-by-column convolution.

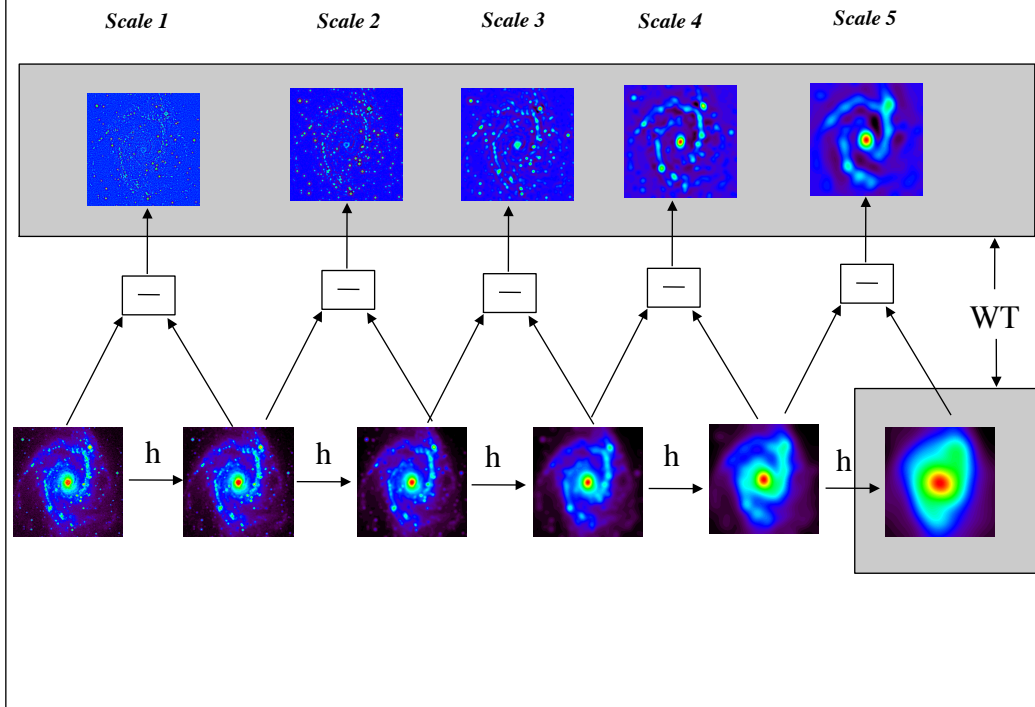
Boundaries

The most general way to handle the boundaries is to consider that $c_{k+N} = c_{N-k}$ (mirror). But other methods can be used such as periodicity ($c_{k+N} = c_k$), or continuity ($c_{k+N} = c_N$).

NGC2997



ISOTROPIC UNDECIMATED WAVELET TRANSFORM



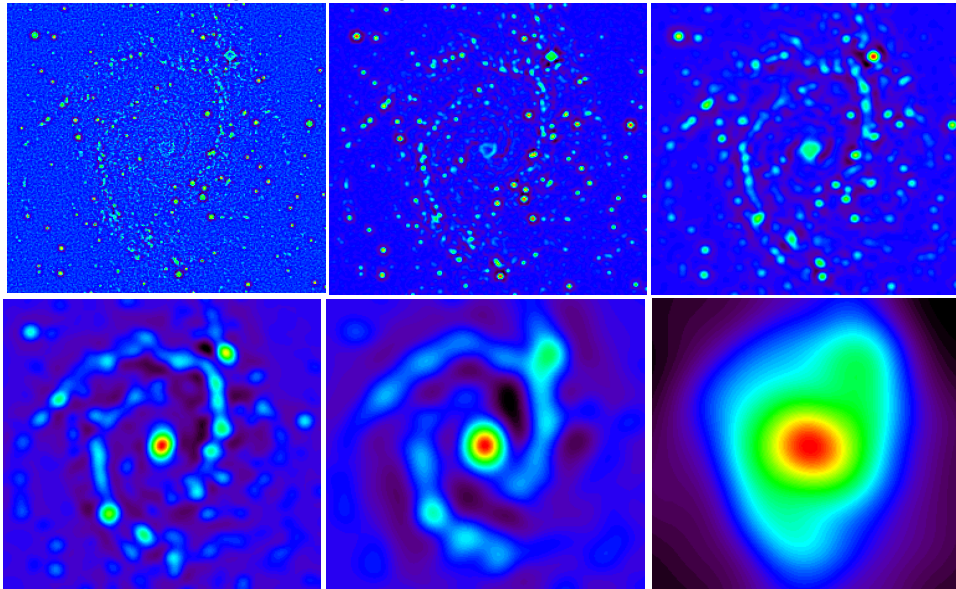
The STARLET Transform

Isotropic Undecimated Wavelet Transform (a trous algorithm)

$$\varphi = B_3 - \text{spline}, \quad \frac{1}{2}\psi\left(\frac{x}{2}\right) = \frac{1}{2}\varphi\left(\frac{x}{2}\right) - \varphi(x)$$

$$h = [1, 4, 6, 4, 1]/16, \quad g = \delta - h, \quad \tilde{h} = \tilde{g} = \delta$$

$$I(k, l) = c_{J, k, l} + \sum_{j=1}^J w_{j, k, l}$$

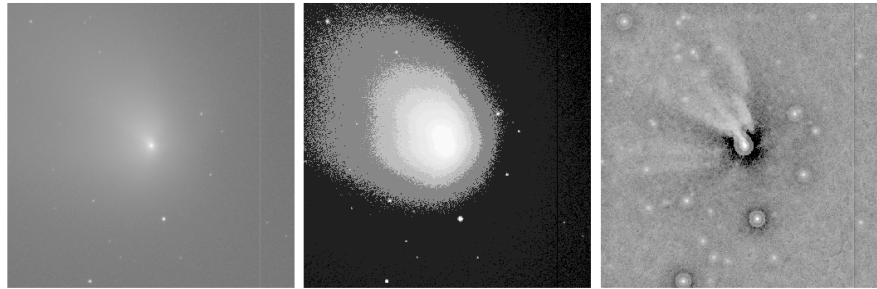


Dynamic Range Compression

Images with a high dynamic range are also difficult to analyze. For example, astronomers generally visualize their images using a logarithmic look-up-table conversion.

Wavelet can also be used to compress the dynamic range at all scales, and therefore allows us to clearly see some very faint features. For instance, the wavelet-log representations consists in replacing $w_{j,k,l}$ by $\log(|w_{j,k,l}|)$, leading to the alternative image

$$I_{k,l} = \log(c_{J,k,l}) + \sum_{j=1}^J \text{sgn}(w_{j,k,l}) \log(|w_{j,k,l}| + \epsilon)$$



Left - Hale-Bopp Comet image. Middle - histogram equalization results, Right - wavelet-log representations.